

Quantum model of allosteric signalling as a non-Markovian effect

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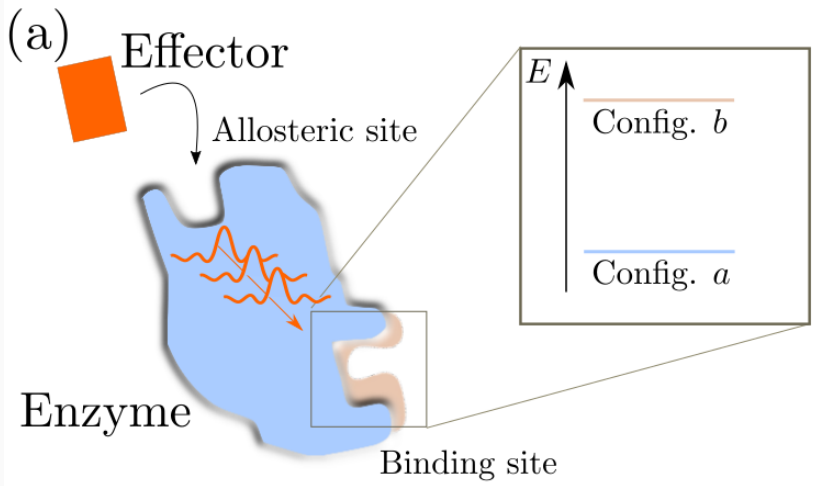


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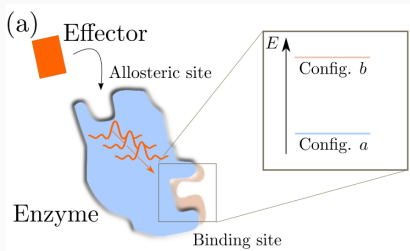


University of
St Andrews

Allostery

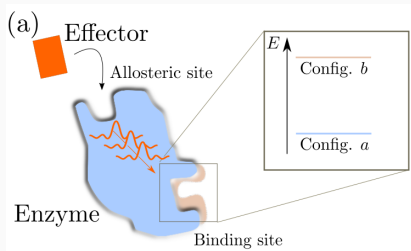


Allostery



Key Properties

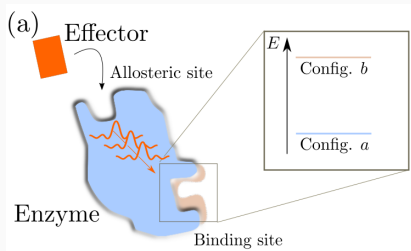
Allostery



Key Properties

- At-a-distance influence

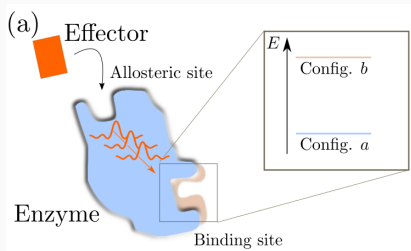
Allostery



Key Properties

- At-a-distance influence
- Reversible

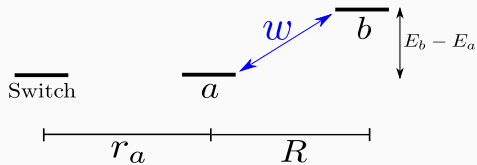
Allostery



Key Properties

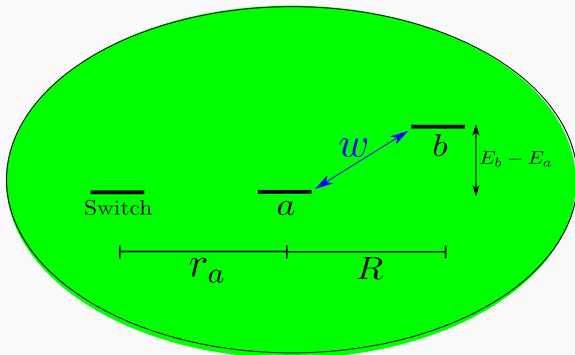
- At-a-distance influence
- Reversible
- Mechanical (?)

Simplified Model



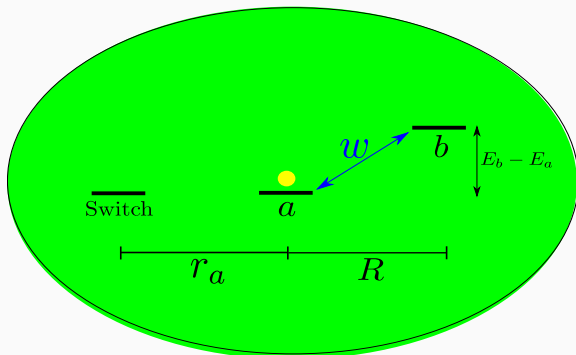
$$\hat{H} = \sum_{\gamma=S,a,b} E_{\gamma} \hat{P}_{\gamma} + w (|a\rangle \langle b| + \text{h.c.})$$

Simplified Model



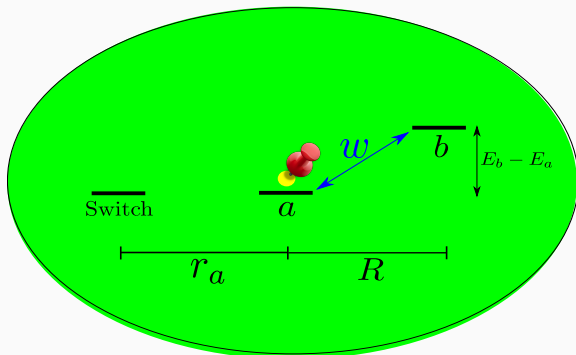
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Simplified Model



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$$+ \sum_{\gamma} s_{\gamma} \hat{P}_{\gamma} \int_{-k_c}^{+k_c} (g_k e^{ikr_{\gamma}} \hat{a}_k + \text{h.c.}) dk ; s_{\gamma} = \pm 1$$

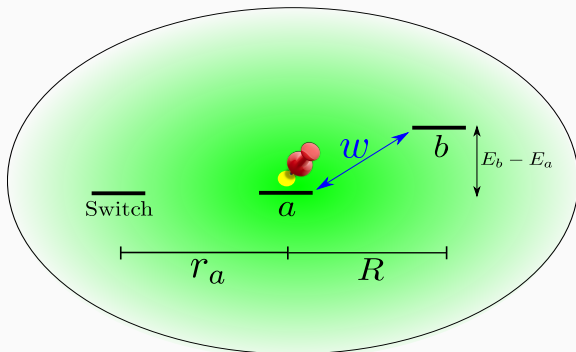
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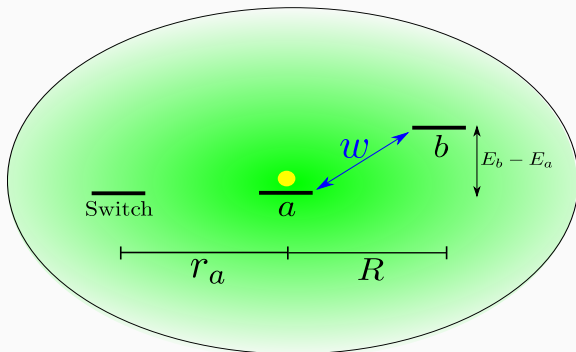
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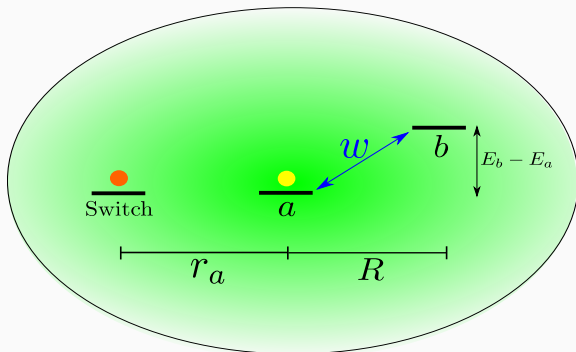
Simplified Model



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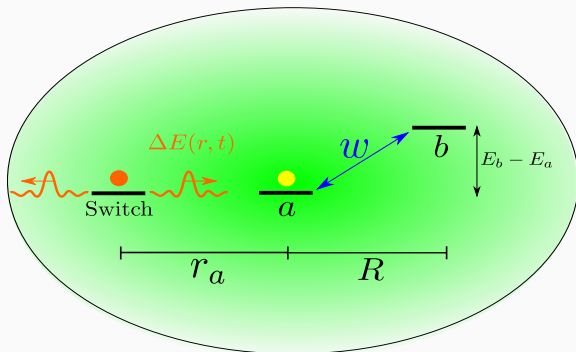
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Simplified Model



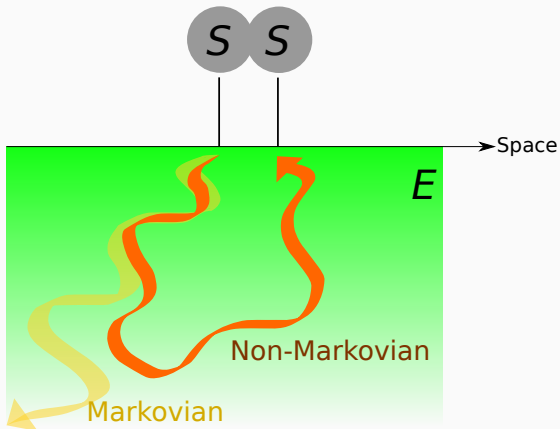
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Shared History Matters

Non-Markovian Environment

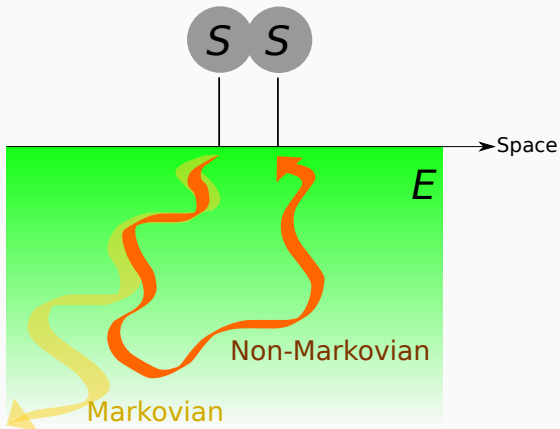
- $T_E \sim T_S$



Shared History Matters

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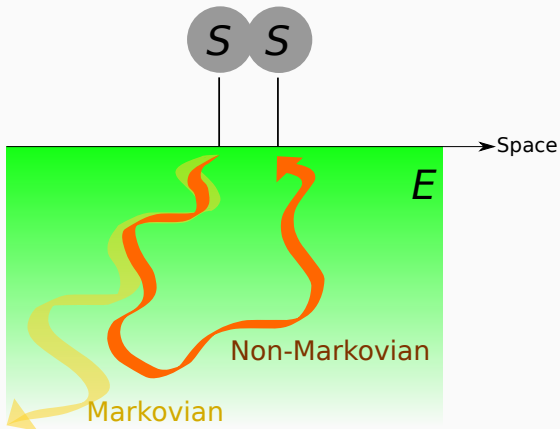
- $T_E \sim T_S$
- Strong Coupling



Shared History Matters

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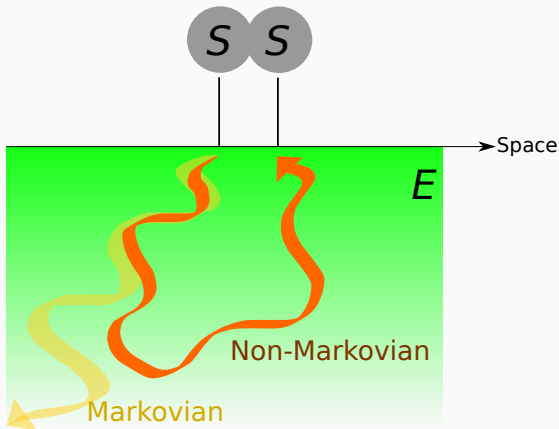
- $T_E \sim T_S$
- Strong Coupling
- Non time-local Master Equations



Shared History Matters

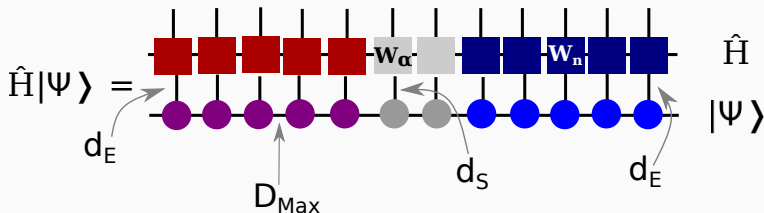
Non-Markovian Environment **is hard to study!**

- $T_E \sim T_S$
- Strong Coupling
- Non time-local Master Equations



Numerically Exact Simulations

Matrix Product State Ansatz for the system-environment wave-function



$$|\psi\rangle = \sum_{\{i_k\}} \sum_{\{\alpha\}} T_{i_1}^{\alpha_1} T_{i_2}^{\alpha_1 \alpha_2} T_{i_3}^{\alpha_2 \alpha_3} \dots T_{i_N}^{\alpha_{N-1}} |\phi_{i_1} \dots \phi_{i_N}\rangle$$

$$\hat{H} = \sum_{\{\sigma\}, \{\sigma'\}, \{w\}} W_{1 w_1}^{\sigma_1 \sigma'_1} W_{2 w_1 w_2}^{\sigma_2 \sigma'_2} \dots W_{N w_{N-1}}^{\sigma_N \sigma'_N} |\sigma_1 \dots \sigma_N\rangle \langle \sigma'_1 \dots \sigma'_N| .$$

Results

Reorganization Dynamics

Pedagogical case: separable state

Reorganization Dynamics

Pedagogical case: separable state

Trace out the bath d.o.f

$$\langle \hat{H}_{\text{int}} \rangle_B = \sum_{\gamma} s_{\gamma} \hat{P}_{\gamma} \left\langle \int_{\mathbb{R}} g_k (\hat{a}_k e^{ikr_{\gamma}} + \text{h.c.}) dk \right\rangle_B = \sum_{\gamma} s_{\gamma} \hat{P}_{\gamma} \Delta E(r_{\gamma}, t) .$$

Reorganization Dynamics

Pedagogical case: separable state

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The interaction Hamiltonian becomes a shift term for the bare sites energies

$$\begin{aligned} \hat{H}_S + \langle \hat{H}_{\text{int}} \rangle_B &= \sum_{\gamma} E_{\gamma} \hat{P}_{\gamma} + w(|a\rangle \langle b| + \text{h.c.}) + \sum_{\gamma} s_{\gamma} \Delta E(r_{\gamma}, t) \hat{P}_{\gamma} \\ &= \sum_{\gamma} (E_{\gamma} + s_{\gamma} \Delta E(r_{\gamma}, t)) \hat{P}_{\gamma} + w(|a\rangle \langle b| + \text{h.c.}) . \end{aligned}$$

Reorganization Dynamics

For a bath with a hard cut-off Ohmic spectral density

$$J(\omega) = 2\alpha\omega H(\omega_c - \omega)$$

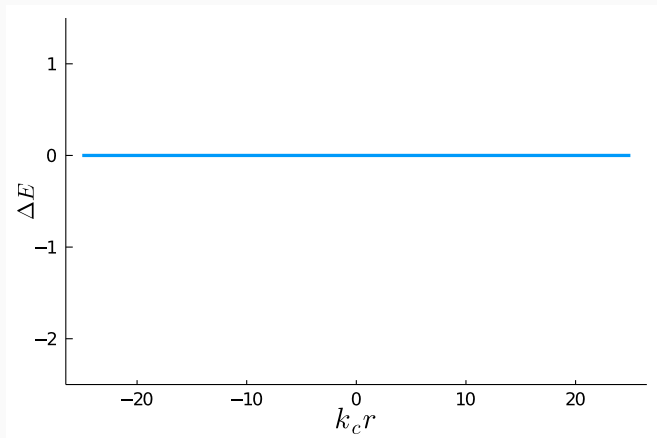
the energy shift takes the form

$$\Delta E(r_\gamma, t) = \frac{-s_\gamma 2\lambda \sin(k_c r_\gamma)}{k_c r_\gamma} + s_\gamma \sum_{\xi=\pm 1} \frac{\lambda \sin(k_c(r_\gamma - \xi ct))}{k_c(r_\gamma - \xi ct)}.$$

With the reorganisation energy $\lambda = \int_{\mathbb{R}} \frac{J(\omega)}{\omega} d\omega = 4\alpha\omega_c$.

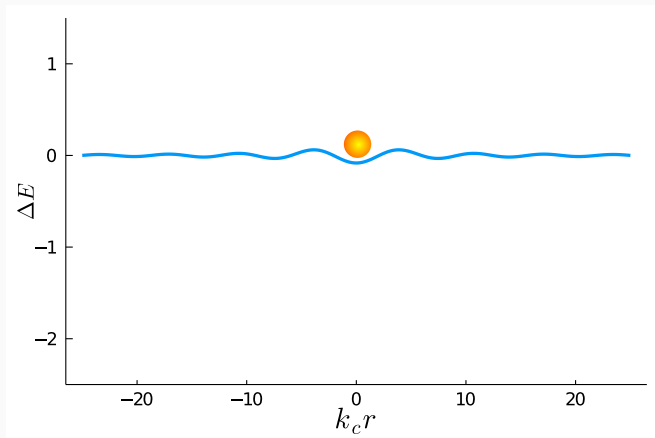
Reorganization Dynamics

$$\Delta E(r_\gamma, t) = \frac{-2\lambda \sin(k_c r_\gamma)}{k_c r_\gamma} + \frac{\lambda \sin(k_c(r_\gamma - ct))}{k_c(r_\gamma - ct)} + \frac{\lambda \sin(k_c(r_\gamma + ct))}{k_c(r_\gamma + ct)}$$



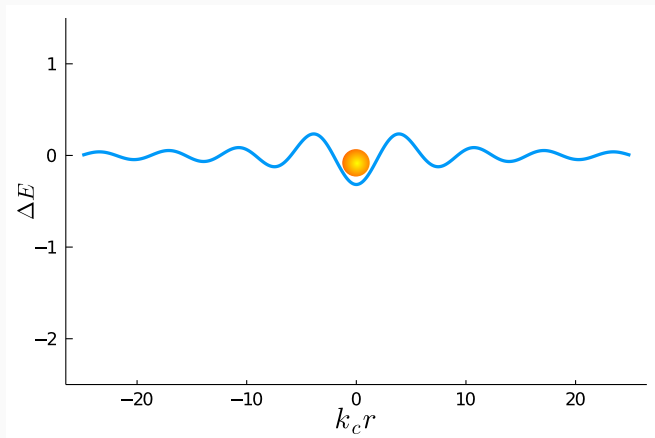
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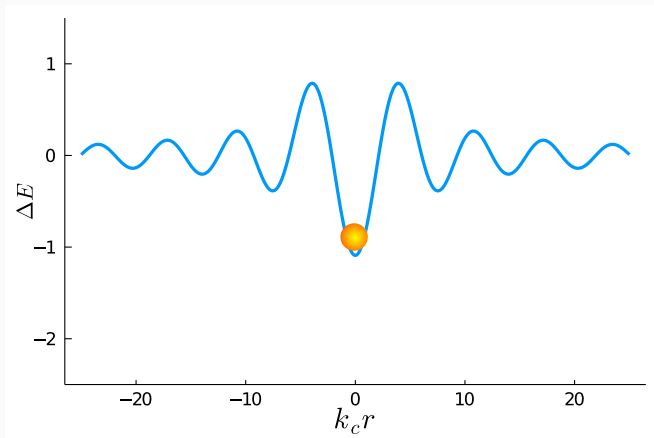
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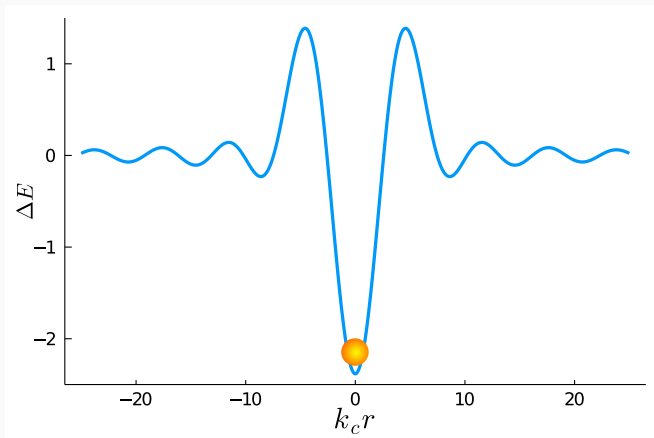
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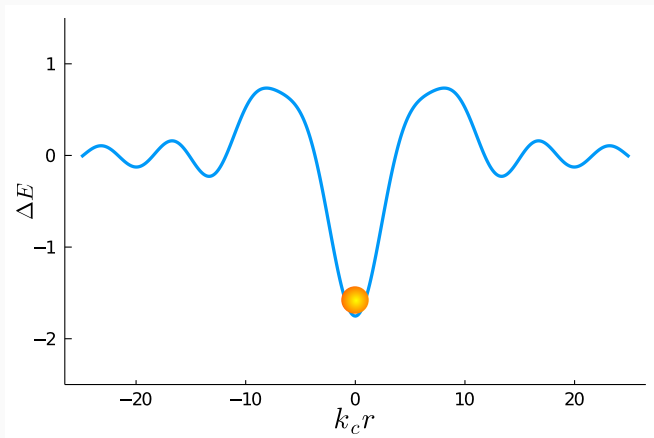
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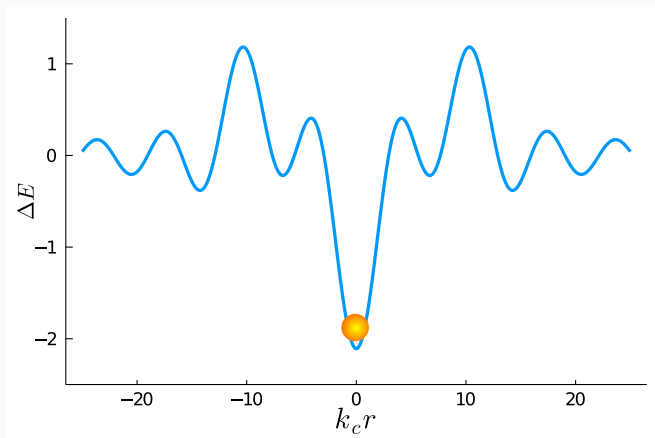
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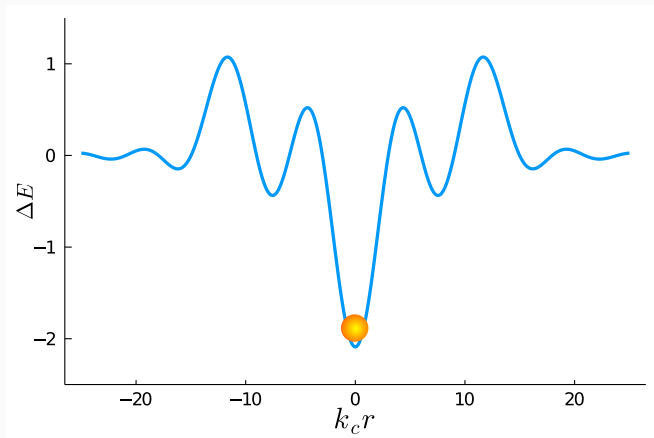
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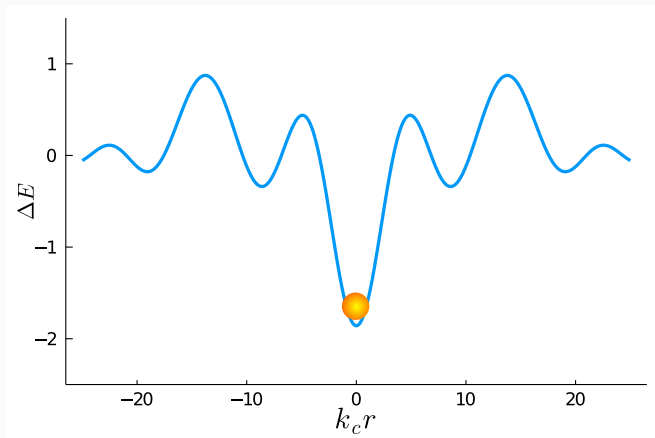
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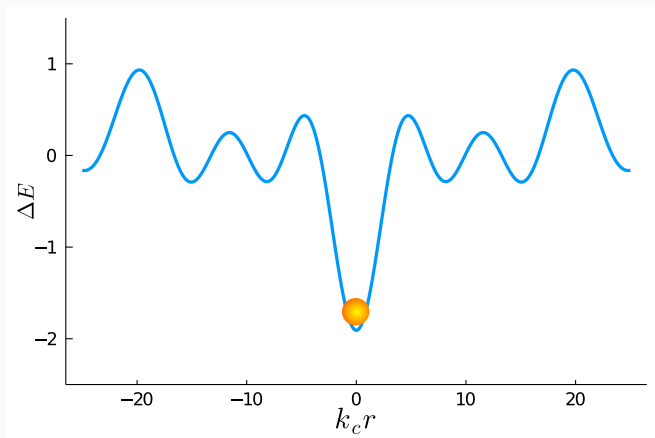
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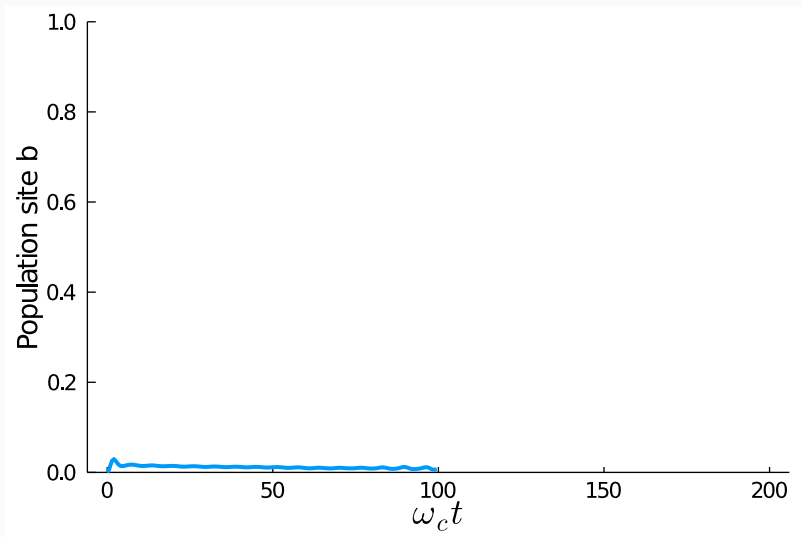


Transient Activation

Reorganized TLS Gap \gg coherent tunneling ($E_b - E_a + 2\lambda \gg w$)

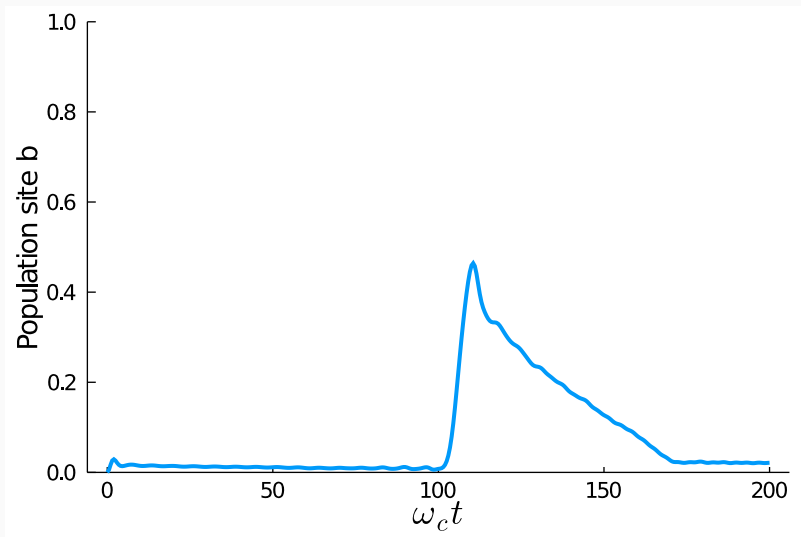
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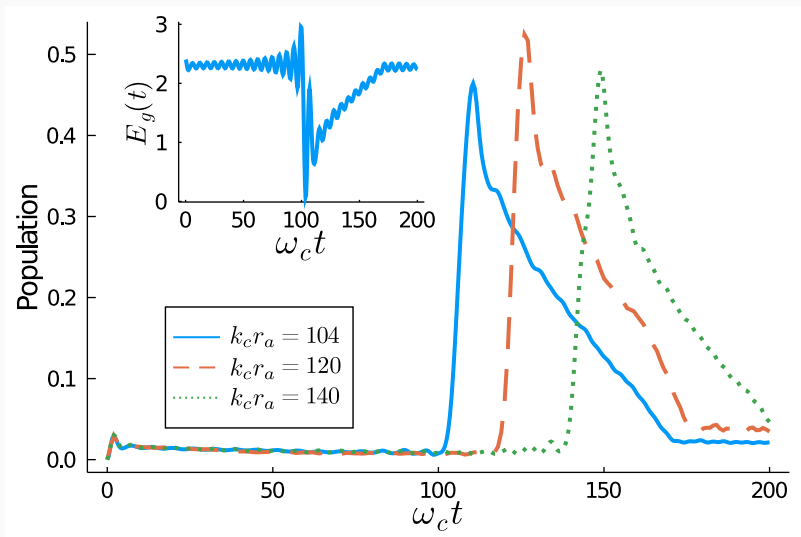
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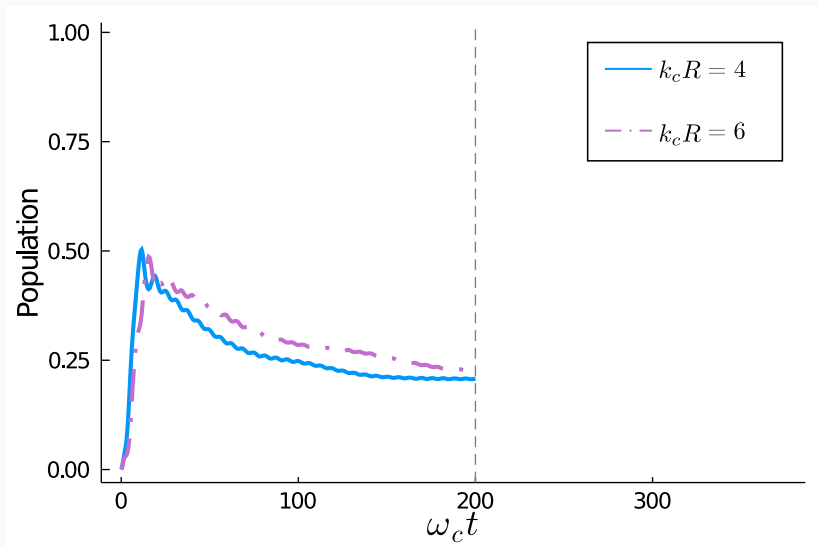


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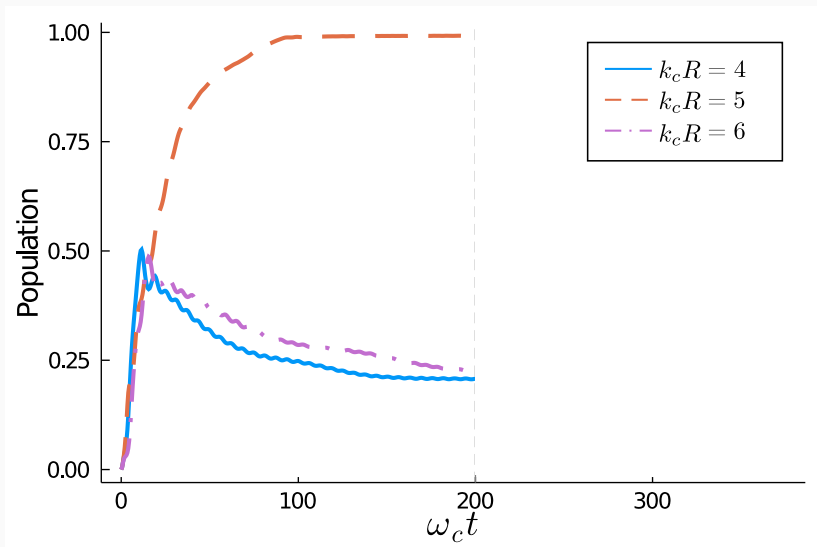
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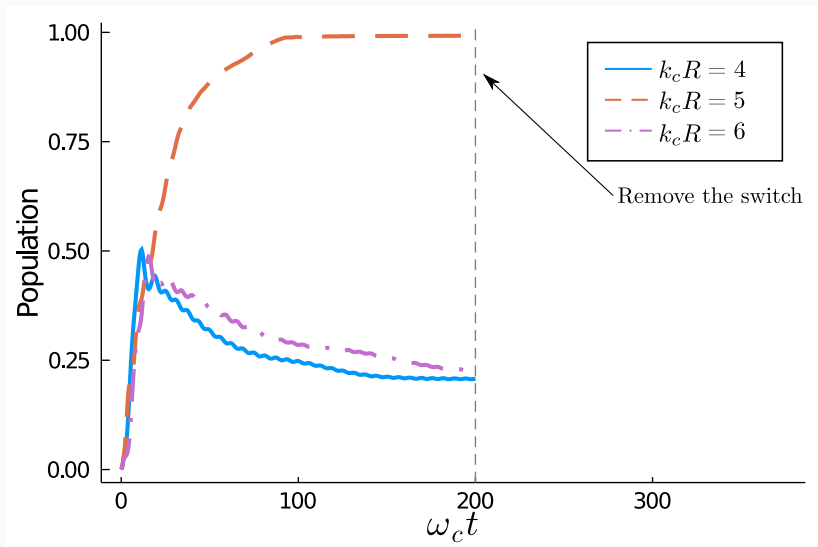
Conformal Activation



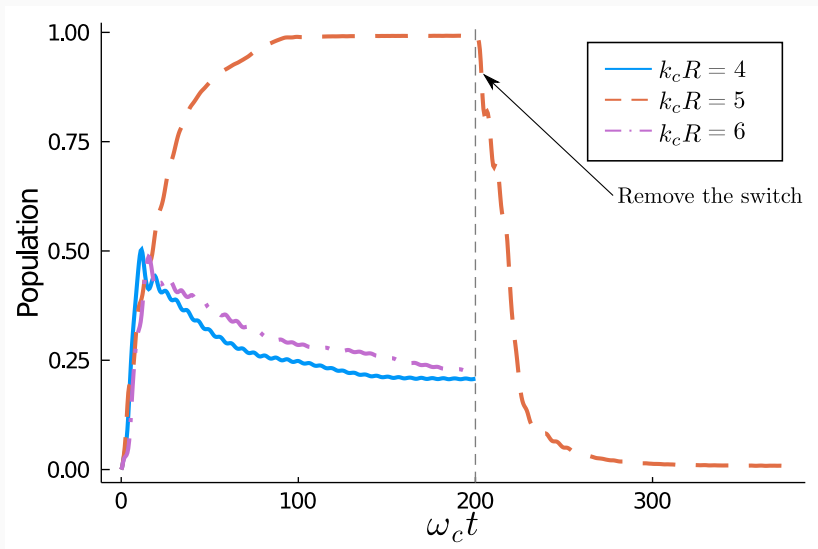
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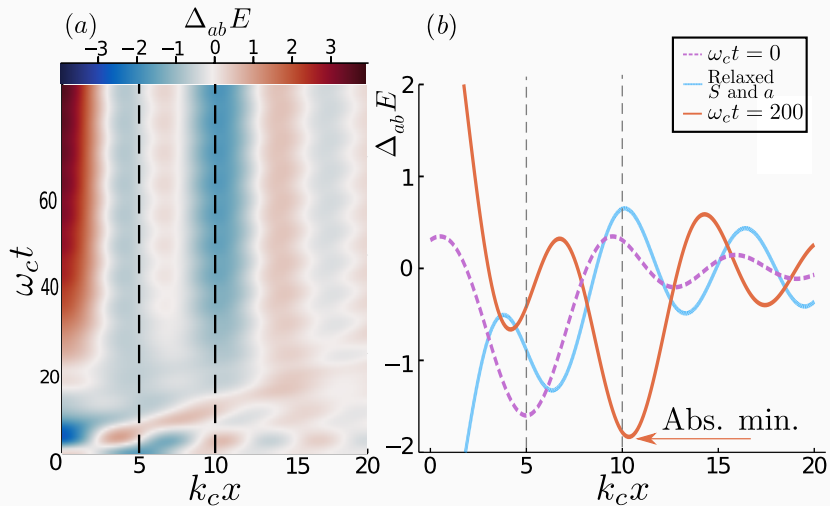
Conformal Activation



Conformal Activation



Reorganization Energy Landscape



Conclusion

Take Away

Take Away

- OQS model of environmentally mediated signalling

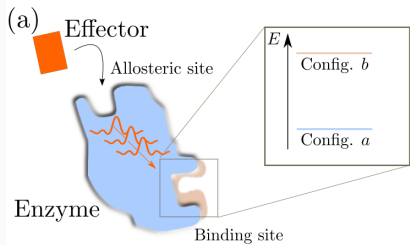
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Conclusion

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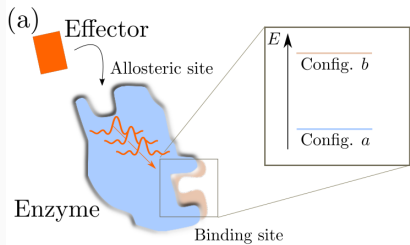
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Conclusion

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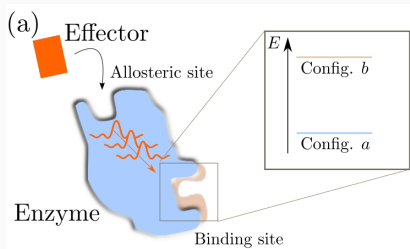
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Conclusion

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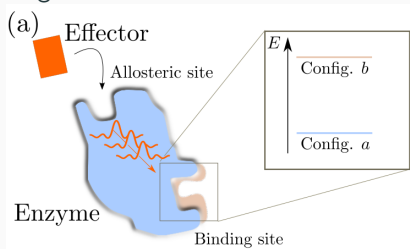
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Conclusion

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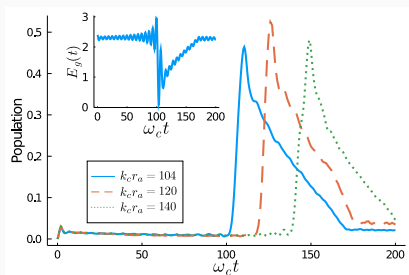
- OQS model of environmentally mediated signalling
- Common features with allosteric regulation
 - ◇ distal control of a transition
 - ◇ reversibility
 - ◇ specific spatial arrangement of allosteric and active sites
 - ◇ mechanical signal



Conclusion

Take Away

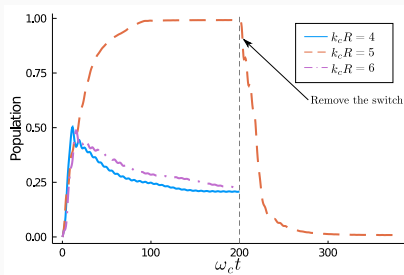
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- Two types of processes
 - ◊ Transient Activation



Conclusion

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- Two types of processes
 - ◇ Transient Activation
 - ◇ Conformal Activation



Take Away


- OQS model of environmentally mediated signalling
- Common features with allosteric regulation
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Outlook

Take Away

- OQS model of environmentally mediated signalling
- Common features with allosteric regulation
- Two types of processes



Outlook

 Purely Quantum Effects?

Take Away

- OQS model of environmentally mediated signalling
- Common features with allosteric regulation
- Two types of processes

Outlook

-  Purely Quantum Effects?
-  Sensing and Control?

Thank you for your attention!

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& A. W. Chin (Sorbonne U./CNRS).

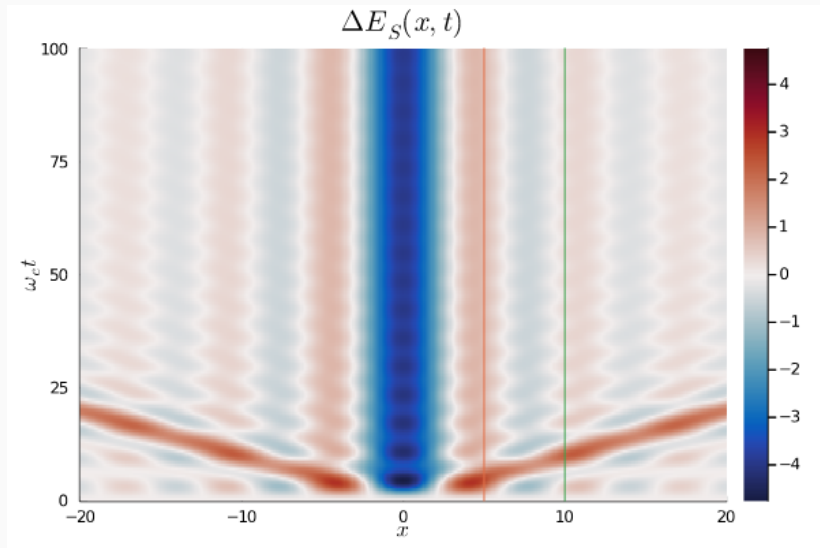
This work is supported by dstl.



<https://arxiv.org/abs/2205.11247>

You want to know more?

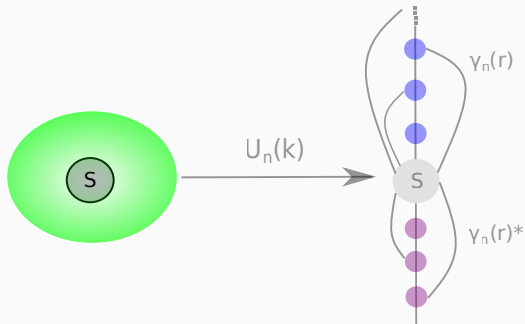
Switch Energy Landscape



Methods

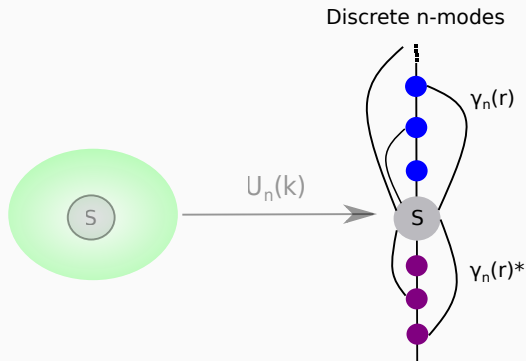
Environment-Chain Mapping

Continuous k-modes



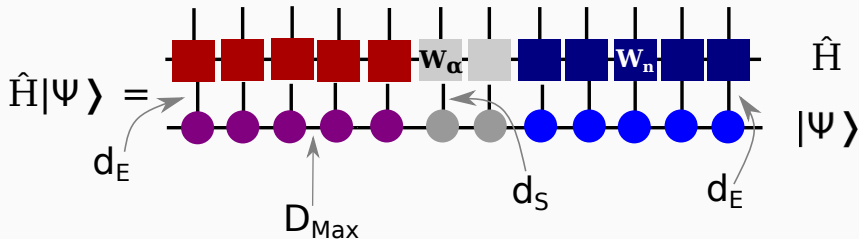
$$\hat{H}_B + \hat{H}_{\text{int}} = \int_{-k_c}^{+k_c} \omega_k \hat{a}_k^\dagger \hat{a}_k dk + \sum_{\alpha} \hat{P}_{\alpha} \int_{-k_c}^{+k_c} (g_k e^{ikr_{\alpha}} \hat{a}_k + \text{h.c.}) dk$$

Environment-Chain Mapping



$$\hat{H}_B + \hat{H}_{\text{int}} = \sum_n \omega_n (\hat{c}_n^\dagger \hat{c}_n + \hat{d}_n^\dagger \hat{d}_n) + t_n (\hat{c}_n^\dagger \hat{c}_{n+1} + \hat{d}_n^\dagger \hat{d}_{n+1} + \text{h.c.}) \\ + \sum_\alpha \hat{P}_\alpha \sum_n \left(\gamma_n(r_\alpha) (\hat{c}_n + \hat{d}_n^\dagger) + \text{h.c.} \right)$$

Tensor Networks

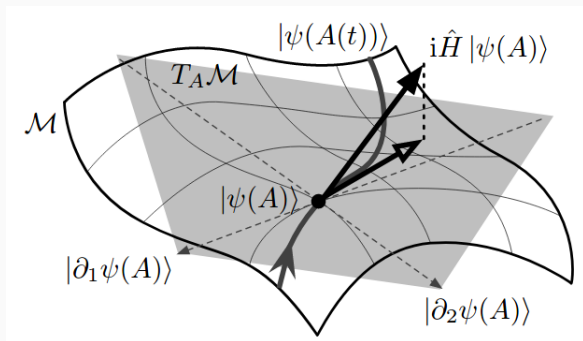


$$|\psi\rangle = \sum_{\{i_k\}} \sum_{\{\alpha\}} T_{i_1}^{\alpha_1} T_{i_2}^{\alpha_1 \alpha_2} T_{i_3}^{\alpha_2 \alpha_3} \dots T_{i_N}^{\alpha_{N-1}} |\phi_{i_1} \dots \phi_{i_N}\rangle$$

$$\hat{H} = \sum_{\{\sigma\}, \{\sigma'\}, \{w\}} W_{1 w_1}^{\sigma_1 \sigma'_1} W_{2 w_1 w_2}^{\sigma_2 \sigma'_2} \dots W_{N w_{N-1}}^{\sigma_N \sigma'_N} |\sigma_1 \dots \sigma_N\rangle \langle \sigma'_1 \dots \sigma'_N| \cdot$$

Time-Dependent Variational Principle

$$\frac{\partial}{\partial t} |\psi\rangle = -i\hat{P}_{T|\psi}\hat{H}|\psi\rangle$$



Haegeman et al., Phys. Rev. Lett. 107(7), 070601 (2011)

Dunnet, *MPSDynamics.jl*, github.com/angusdunnett/MPSDynamics/

Matrix Product Operator I

The matrices W_k define the Hamiltonian MPO

$$\hat{H} = \sum_{\{\sigma\}, \{\sigma'\}, \{w\}} W_{1 w_1}^{\sigma_1 \sigma'_1} W_{2 w_1 w_2}^{\sigma_2 \sigma'_2} \cdots W_{N w_{N-1}}^{\sigma_N \sigma'_N} |\sigma_1 \dots \sigma_N\rangle \langle \sigma'_1 \dots \sigma'_N| .$$

with, for the system

$$W_{1 < \alpha \leq N} = \begin{pmatrix} \hat{\mathbb{I}} & J \hat{f}_\alpha & J \hat{f}_\alpha^\dagger & 0 & 0 & \underbrace{\dots}_{2(\alpha-2)} & |\alpha\rangle \langle \alpha| & |\alpha\rangle \langle \alpha| & E_\alpha \hat{P}_\alpha \\ & & & 0 & & & & & \hat{f}_\alpha^\dagger \\ & & & 0 & & & & & \hat{f}_\alpha \\ & & & \hat{\mathbb{I}} & & & & & 0 \\ & & & & \hat{\mathbb{I}} & & & & 0 \\ & & & & & \ddots & & & \vdots \\ & & & & & & 0 & 0 & 0 \\ & & & & & & & & \hat{\mathbb{I}} \end{pmatrix}$$

Matrix Product Operator II

And for the environment

$$W_{1 \leq n \leq N_m} = \begin{pmatrix} \hat{\mathbb{1}} & t_n \hat{c}_n^\dagger & t_n \hat{c}_n & 0 & 0 & \dots & 0 & \omega_n \hat{c}_n^\dagger \hat{c}_n \\ & & & 0 & & & & \hat{c}_n \\ & & & 0 & & & & \hat{c}_n^\dagger \\ & & & \hat{\mathbb{1}} & & & & \gamma_n^1 \hat{c}_n \\ & & & & \hat{\mathbb{1}} & & & \gamma_n^{1*} \hat{c}_n^\dagger \\ & & & & & \ddots & & \vdots \\ & & & & & & \hat{\mathbb{1}} & \gamma_n^{N*} \hat{c}_n^\dagger \\ & & & & & & & \hat{\mathbb{1}} \end{pmatrix}$$